READEX: A Tool Suite for Dynamic Energy Tuning

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SuperMUC: 3 Petaflops, 3 MW







Runtime Exploitation of Application Dynamism for Energy-efficient eXascale Computing 09/2015 to 08/2018

www.readex.eu

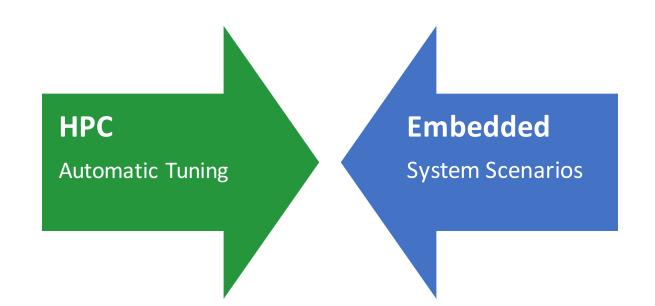




European Commission

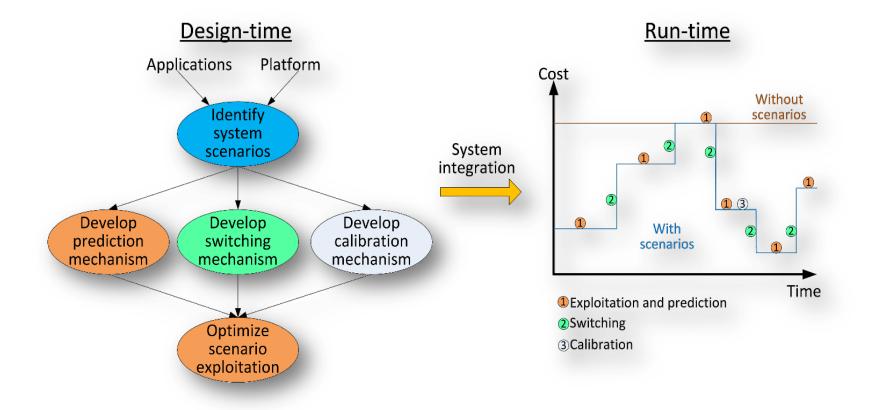
Objectives

- Tuning for energy efficiency
- Beyond static tuning: exploit dynamism in application characteristics
- Leverage system scenario based tuning





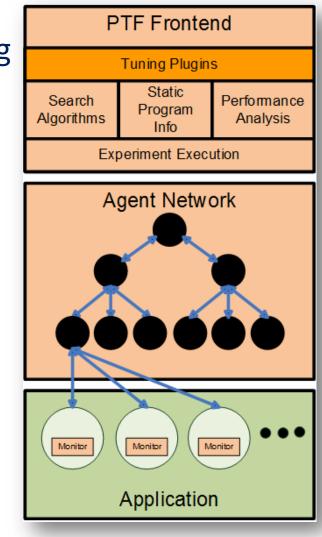
Systems Scenario based Methodology





Periscope Tuning Framework (PTF)

- Automatic application analysis & tuning
 - Tune performance and energy (statically)
 - Plug-in-based architecture
 - Evaluate alternatives online
 - Scalable and distributed framework
- Support variety of parallel paradigms
 - MPI, OpenMP, OpenCL, Parallel pattern
- AutoTune EU-FP7 project

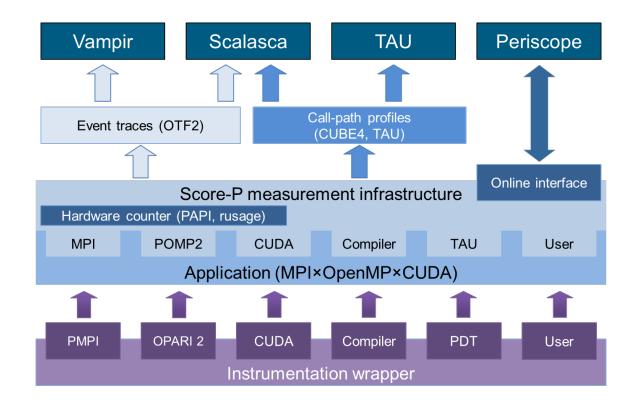






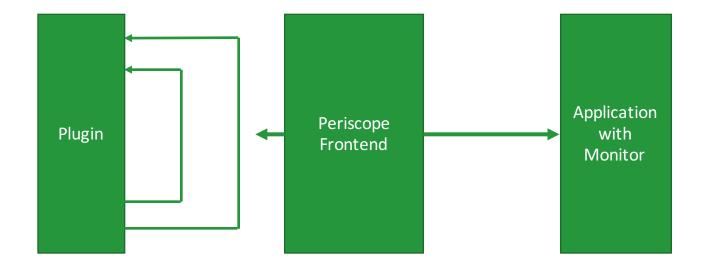


Scalable Performance Measurement Infrastructure for Parallel Codes Common instrumentation and measurement infrastructure





Tuning Plugin Interface



Search Space Exploration inside of Tuning Steps

Scenario execution

- Tuning actions
- Measurement requests





Tuning Plugins

- MPI parameters
 - Eager Limit, Buffer space, collective algorithms
 - Application restart or MPIT Tools Interface
- DVFS
 - Frequency tuning for energy delay product
 - Model-based prediction of frequency
 - Region level tuning
- Parallelism capping
 - Thread number tuning for energy delay product
 - Exhaustive and curve fitting based prediction



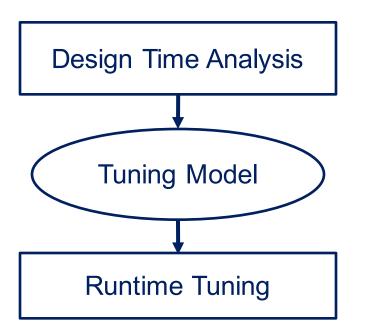


Dynamic Tuning with the READEX Tool Suite

- READEX extends the concept of tuning in Periscope
- Dynamic tuning
 - Instead of one optimal configuration, SWITCH between different best configurations.
 - Dynamic adaptation to changing program characteristics.







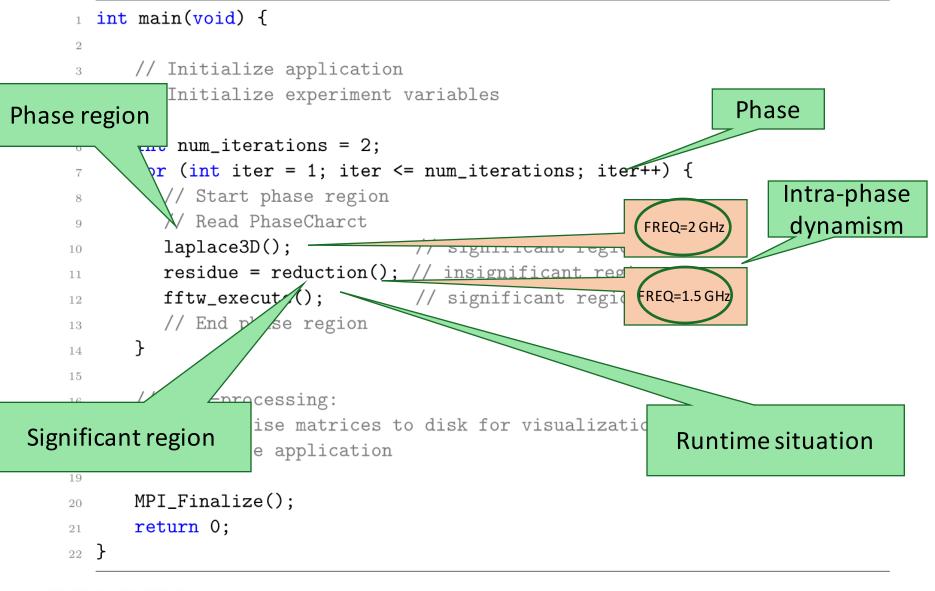
Periscope Tuning Framework (PTF)

READEX Runtime Library (RRL)





Intra-phase Dynamism







READEX Intra-phase Tuning Plugin

Tuning plugin supporting

- Core and uncore frequencies, numthreads parameters, application tuning parameters
- Configurable search space via READEX Configuration File
- Several objective functions: energy, CPUenergy, EDP, EDP2, time
- Several search strategies: exhaustive, individual, random, genetic

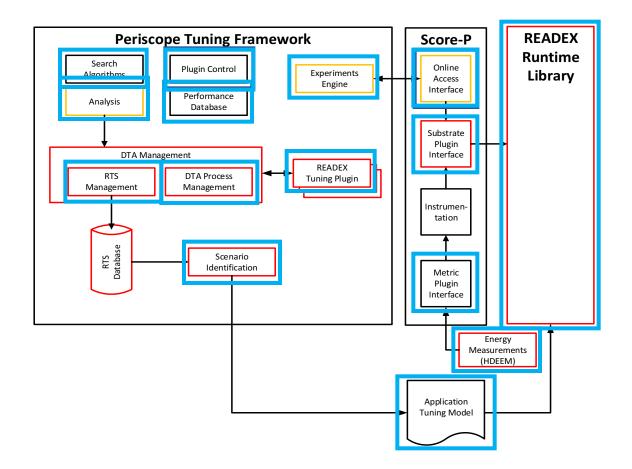
Approach

- 1. Experiment with default configuration
- 2. Experiments for selected configurations
 - Configuration set for phase region
 - Energy and time measured for all runtime situations
- 3. Identification of static best for phase and rts specific best configurations





Pre-Computation of Tuning Model



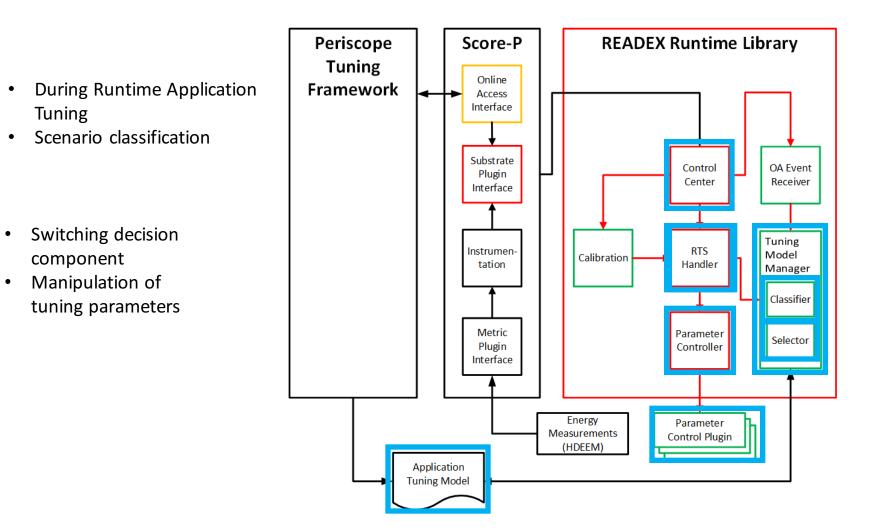


READEX **R**untime Library (RRL)

- Runtime Application Tuning performed by the READEX Runtime Library.
- Tuning requests during Design Time Analysis are sent to RRL.
- A lightweight library
 - Dynamic switching between different configurations at runtime.
 - Implemented as a substrate plugin of Score-P.
- Developed by TUD and NTNU



Runtime Scenario Detection and Switching Decision during Production Run







BEM4I – Dynamic switching – Energy

http://bem4i.it4i.cz/

	assemble_k	assemble_v	gmres_solve	print_vtu	main
blade summary, energy	[1]	[J]	[J]	[J]	[1]
default settings	1467	1484	2733	1142	6872
static tuning only	1876	1926	1306	402	5537
dynamic tuning only	1348	1335	1150	268	4138
static + dynamic tuning	1343	1322	1161	265	4125
static savings [%]	-27.9%	-29.8%	52.2%	64.8%	+19.4%
dynamic savings [%]	8.4%	10.9%	57.5%	76.8%	+40.0%
static + dynamic savings [%]	8.1%	10.0%	57.9%	76.5%	+39.8%

"static": {

},

"FREQUENCY": "25",

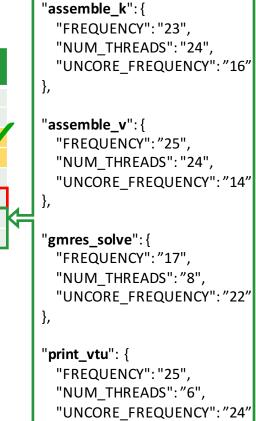
<----- 2.5 GHz

"NUM_THREADS": "12",

<----- 12 OpenMP threads

"UNCORE FREQUENCY": "22"

<----- 2.2 GHz







Scalability Tests – OpenFOAM – Analysis

simpleFoam

- strong scaling test
- Motorbike example
- optimum detected for every run
- Static: 11.7%
- Dynamic: 4.4%
- Total: 15.5%
- Dynamic savings increases with higher number of nodes

	Default energy	Default time	Best static configuration	Static savings	Dynamic savings	Overall savings
1 node	$37864.34{ m J}$	$113.1\mathrm{s}$	2.2 GHz UCF, 1.6 GHz CF	7344.46 J (19.40%)	105.85 J of 30519.88 J (0.35%)	7450.31 J (19.68%)
2 nodes	$37229.74\mathrm{J}$	$57.99\mathrm{s}$	2.2 GHz UCF, 1.6 GHz CF	$6175.44\mathrm{J}$ (16.59%)	118.24 J of 31054.3 J (0.38%)	6293.68 J (16.9%)
4 nodes	38158.96 J	$30.04\mathrm{s}$	2.0 GHz UCF, 1.8 GHz CF	6223.96 J (16.31%)	107.28 J of 31935.0 J (0.34%)	6331.24 J (16.59%)
8 nodes	$41179.44\mathrm{J}$	$19.48\mathrm{s}$	2.0 GHz UCF, 1.8 GHz CF	4493.2 J (10.91%)	945.12 J of 36686.24 J (2.58%)	5438.32 J (13.21%)
16 nodes	57980.96 J	$14.86\mathrm{s}$	2.2 GHz UCF, 1.8 GHz CF	6780.96 J (11.70%)	2224.96 J of 51200.0 J (4.35%)	9005.92 J (15.53%)
32 nodes	$90374.4\mathrm{J}$	$16.498\mathrm{s}$	2.2 GHz UCF, 1.4 GHz CF	22944.0 J (25.39%)	7113.6 J of 67430.4 J (7.87%)	30057.6 J (33.26%)





Inter-phase Dynamism

0

0.6 8 16 0.5 24 0.4 MPI rank Time [s] 32 0.3 40 0.2 48 56 0.1 200 400 600 800 1000 1200 1400 1600 1800 2000 Iteration number

PEPC Benchmark of the DEISA Benchmark Suite



All-to-all

Performance

2048 phases



Inter-Phase Analysis

- Variation of behavior among phases
- Group/cluster phases
- Select a best configuration for each cluster of phases

What do we need?

- Identifiers of phase characteristics (Phase Identifiers)
- Provided by application expert (??)

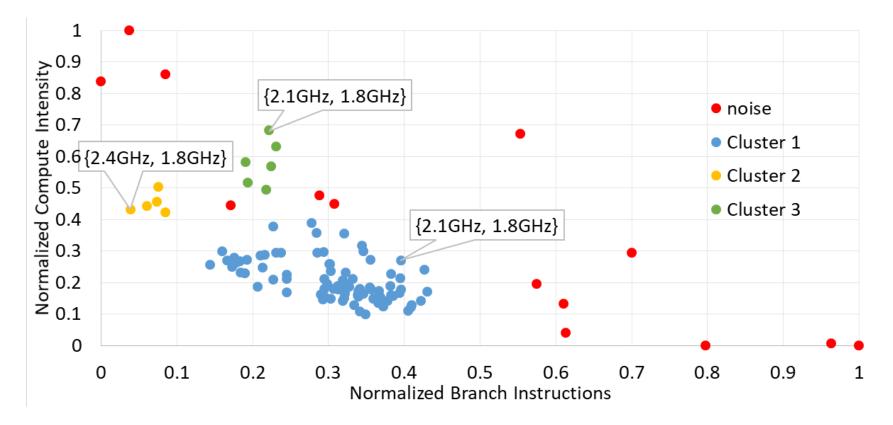


Inter-Phase Analysis – Approach

- Developed the *interphase_tuning* plugin
- 3 tuning steps:
 - Analysis step:
 - Random search strategy is used to create the search space
 - Don't want to explore the whole tuning space
 - Cluster phases and find best configuration for each cluster
 - Default step:
 - Run the application for the default setting
 - Verification step:
 - Select the best configuration for each phase, as determined for its cluster.
 - Aggregate the savings over the phases



INDEED



- 3 clusters identified
- Noise points marked in red



Cluster Prediction in RRL

- How to handle phase identifiers to predict clusters?
 - Call path of an rts now includes the cluster number
- Solution:
 - Add the cluster number as a user parameter
 - Add PAPI events to measure L3_TCM, Total_Instr and conditional branch instructions

```
...
SCOREP_OA_PHASE_BEGIN()
SCOREP_USER_PARAMETER_INT64(cluster, predict_cluster())
...
SCOREP_OA_PHASE_END()
```

- Predict the cluster of the upcoming phase
- If the cluster was mispredicted for the phase, correct it at the end of the phase





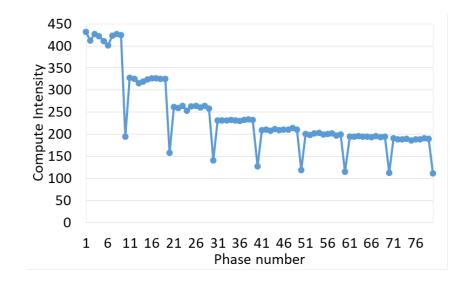
Evaluation of the readex_interphase plugin

- Performed on two applications: miniMD, INDEED
- Experiments conducted on the Taurus HPC system at the ZIH in Dresden
- Each node contains two 12-core Intel Xeon CPUs E5-2680 v3 (Intel Haswell family)
- Runs with a default CPU frequency of 2.5 GHz, uncore frequency of 3 GHz
- Energy measurements provided on Taurus via HDEEM measurement hardware
- Provides processor and blade energy measurements



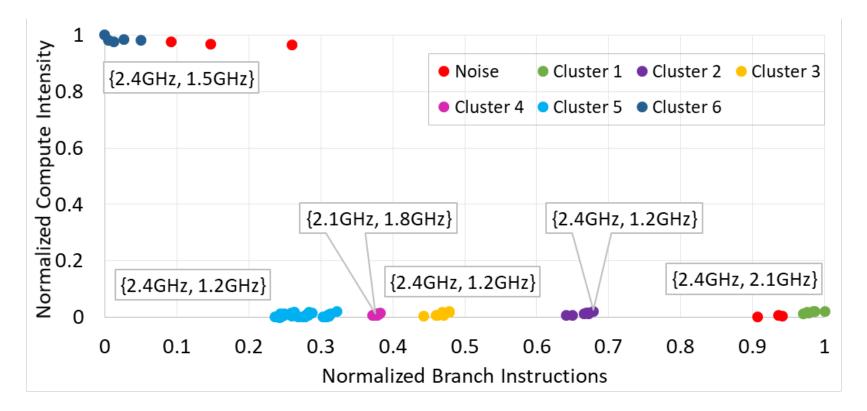
miniMD

- Lightweight, parallel molecular dynamics simulation code
- Performs molecular dynamics simulation of a Lennard-Jones Embedded Atom Model (EAM) system
- Written in C++
- Provides input file to specify problem size, temperature, timesteps
- Evaluation of DTA:
 - Hybrid (MPI+OpenMP) AVX vectorized version
 - Problem size of 50 for the Lennard-Jones system.





miniMD (2)



- 6 clusters identified
- Noise points marked in red



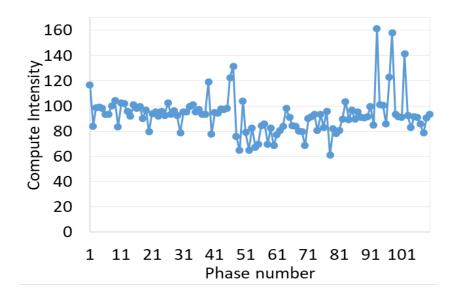
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Dalagna



INDEED

- INDEED performs sheet metal forming simulations of tools with different geometries moving towards a stationary workpiece
- Contact between tool and workpiece causes:
 - Adaptive mesh refinement
 - Increase in number of finite element nodes
 - Increasing computational cost
- Time loop computes the solution to a system of equations until equilibrium is reached.
- OpenMP version evaluated





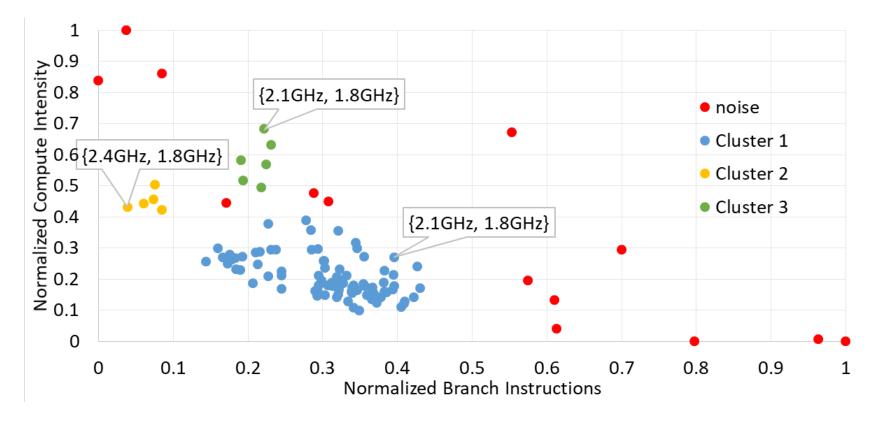
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INDEED (2)



- 3 clusters identified
- Noise points marked in red •



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Energy Savings

Application	Phase best for the rts's (%)	rts best for the rts's (%)
miniMD	14.51	0.03
INDEED	9.24	10.45

- miniMD records lower dynamic savings
 - miniMD has only two significant regions
 - One region is called only once during the entire application run
- Better static and dynamic savings for the rts's of INDEED
 - INDEED has nine significant regions
 - Provides more potential for dynamism





Application Tuning Parameters (ATP)

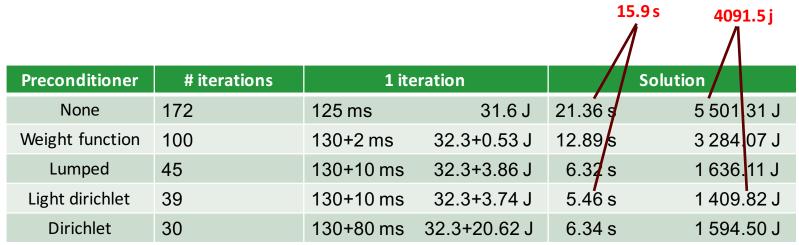
- Exploit the dynamism in characteristics through the use of different code paths (e.g. preconditioners)
- Identify the control variables responsible for control flow switching.
 - provides APIs to annotate the source code





Evaluation of ATP: Espreso

- Finite Element (FEM) tools and domain decomposition based Finite Element Tearing and Interconnect (FETI) solver
 - Contains a projected conjugate gradient (PCG) solver.
 - Convergence can be improved by several preconditioners.
- Evaluated preconditioners on a structural mechanics problem with 23 million unknowns
 - On a single compute node with 24 MPI processes.







Configuration Variable Tuning

- Recently added readex_configuration tuning plugin
- Application Configuration Parameters with search space
- Replace selected value in input files and rerun the application



Input Identifiers

- What about different inputs?
- Annotation with *Input Identifiers* like problem size
- Apply Design Time Analysis and merge generated tuning models
- Selection at runtime based on the input identifiers



Summary

- Energy-efficiency tuning
 - Design Time Analysis Tuning Model Runtime Tuning
- Support for
 - Intra-phase dynamism
 - Inter-phase dynamism
 - Application Tuning Parameters
 - Application Configuration Parameters
 - Different input configurations
- Based on
 - Periscope Tuning Framework
 - Score-P Monitoring





Thank you! Questions?



